

# Electropneumatic positioner APIS

- ✓ HART protocol
- ✓ ATEX certificate  $\text{Ex II 2G Exia IIC T5/T6 Gb}$
- ✓ Simple in installation and programming
- ✓ Possibility of remote assembling of positioner
- ✓ Low air consumption
- ✓ Programmable speed of movement of the actuator's piston rod
- ✓ Position transmitter
- ✓ Possibility of manual controlling of position of actuator's piston rod

*one device for  
linear and rotational  
actuators*



## Technical data

|   |   |
|---|---|
| Input signal (control)                    | 4...20mA + Hart   |
| Output signal (position transmitter)      | 4...20mA  |
| Supply of position transmitter            | 10÷36 VDC (Ex 10÷30 VDC)  |
| Supply pressure                           | 140÷800 kPa   |
| Pneumatic input signal (control actuator) | 0...100% of supply pressure   |
| Own air consumption                       | ≤ 0,035 kg/h at supply voltage 140 kPa<br>≤ 0,015 kg/h at supply voltage 600 kPa<br>≥ 3,25 kg/h at supply voltage 140 kPa<br>≥ 13kg/h at supply voltage 800 kPa |
| Air mass stream on positioner output      |   |
| Actuator piston rod displacement range    | 10÷100 mm (for single-acting linear actuators)<br>80÷900 mm (for double-acting linear actuators)<br>0÷180° (for rotational actuators)                           |
| Actuator operation characteristics        | linear  |
| Positioner operation mode                 | normal or reversible  |
| Positioner transducer mode                | normal or reversible  |
| Additional errors                         | < 0,05% / 100kPa  |
| - from supply pressure changes            | 0,15% / 10°C – for temperature range -30°C÷+60°C  |
| - from ambient temperature changes        | 0,25% / 10°C – for temperature range -40°C÷-30°C and +60°C÷+85°C  |
| - from vibration in range:                |   |
| 10...60Hz, amplitude < 0,35 mm            |   |
| 60...500Hz, acceleration 5g               | 0,25%   |
| Hysteresis                                | < 0,4%  |
| Insensibility threshold                   | < 0,1%  |
| Protection degree of positioner enclosure | IP 65 according to PN-EN 60529:2003   |
| Operation position                        | any   |
| Weight                                    | 1,8 kg  |

## Operating conditions

|   |  |
|---|--|
| Working medium  | air free of dust, oil, aggressive pollutants, solid particles bigger than 1.5 µm, such relative humidity not lower that dew point's temperature should not be lower than 10 °C with respect to ambient temperature (acc. to PN-EN 60654-2:1999). |
| Ambient temperature   |  |
| Execution without manometers and with stainless steel manometers: | -40°C÷+85°C  |
| Executions with manometers in stainless steel                     |  |
| Humidity of ambient air   | < 95%  |
| Allowable vibrations  | acc. to PN-EN 60654-3: 1997; class VH6   |
| 10...60Hz,  | amplitude < 0,35 mm  |
| 60...500Hz  | acceleration ≤ 5g  |

## Ordering procedure

APIS - X X X - DXX - RXX - IHE - TXX - PX - MX - WX - AX

### Intend use:

- for single-operating actuator..... 1
- for double-operating actuator..... 2
  
- for installation on actuator..... 0
- for installation outside actuator with
  - external position transmitter (potentiometer) – IP54 <sup>1)</sup>... 1
  - external position transmitter (potentiometer) – IP67 <sup>1)</sup>... 2
  - external position transmitter (magnetic) – IP67 <sup>1), 2)</sup>... 3
  - external position transmitter (potentiometer) – IP65 <sup>3)</sup>... 4

### Distance of positioner from actuator:

- ... m (0 ÷ 15 m)..... XX

### Execution:

- standard..... St
- intrinsically safe II 2G Exia IIC T6/T5 Gb..... EX

### Analog position transmitter:

- without position transmitter..... 00
- with output signal 4+20 mA <sup>4)</sup>..... 20

### Pneumatic connectors:

- connectors to brass pipes ø6 mm..... 1
- connectors to stainless steel pipes ø6 mm..... 2
- connectors to Polyethylene pipes ø6 mm..... 3
- connectors to brass pipes ø8 mm..... 4
- connectors to stainless steel pipes ø8 mm..... 5
- connectors to Polyethylene pipes ø8 mm..... 6
- connectors to Polyethylene pipes ø6 mm (ERMETO)..... 7
- other..... 8

### Manometers:

- with manometers in st. steel execution  
(Ø 40 mm, st. steel housing, glass window)..... 2
- with manometers in st. steel execution and st. steel  
wetted parts (Ø 40 mm, glass window)..... 3
- other..... 4

### Electrical entry:

- plastic packing gland (Ø 4 ÷ 9 mm cable)..... 1
- nicked brass packing gland (Ø 4 ÷ 9 mm cable)..... 2
- other..... 3

### Mounting kit:

- without mounting kit..... 0
- with mounting kit (code according to below table)..... 1

<sup>1)</sup> For double-operating linear actuator.

<sup>2)</sup> Not available with ATEX

<sup>3)</sup> For single-operating linear diaphragm actuators and single and double-operating rotational actuators

<sup>4)</sup> The positioner can set reverse of analogue output signal (20...4 mA). The reverse function of the output signal is switched on programmatically by the user.

| Mounting kit |              | Type of actuator   |
|--------------|--------------|--|
| APIS-A000    | For APIS-100 | Type P or R, Polna S.A. (mounted on the columns)   |
| APIS-A001    |              | Type 37 or 38, Polna S.A. (yoke)   |
| APIS-A002    |              | Type P1 or R1, Polna S.A. (diaphragm multi-spring)   |
| APIS-A003    |              | Actuator acc. PN-EN 60534-6-1:2001 (Samson, Arca Regler)   |
| APIS-A05X    | For APIS-X00 | Actuator acc. EN ISO 5211, DIN 3337, VDI/VDE 38450 Namur, (Air Torque, Ebro-Armaturen, EI-O-Matic) |
| APIS-AXXX    | For APIS-201 | Actuator acc. ISO 6431 (CNOMO Prema Kielce)  |
|              | -SS          | Material: stainless steel  |
|              | -SO          | Material: zinced steel   |